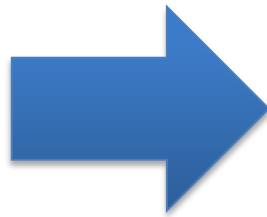


クラス図

Pole_Escape

SearchP2
WatingKobuki
Straight1,2...
TurnLeft1,2...
TurnRight1,2...
SetDirP2
Forward
Stop

```
kobuki_set_wheel(SPEED_HI,-60)
kobuki_set_wheel(0,0)
kobuki_set_wheel(SPEED_HI,0)
      .
      .
```



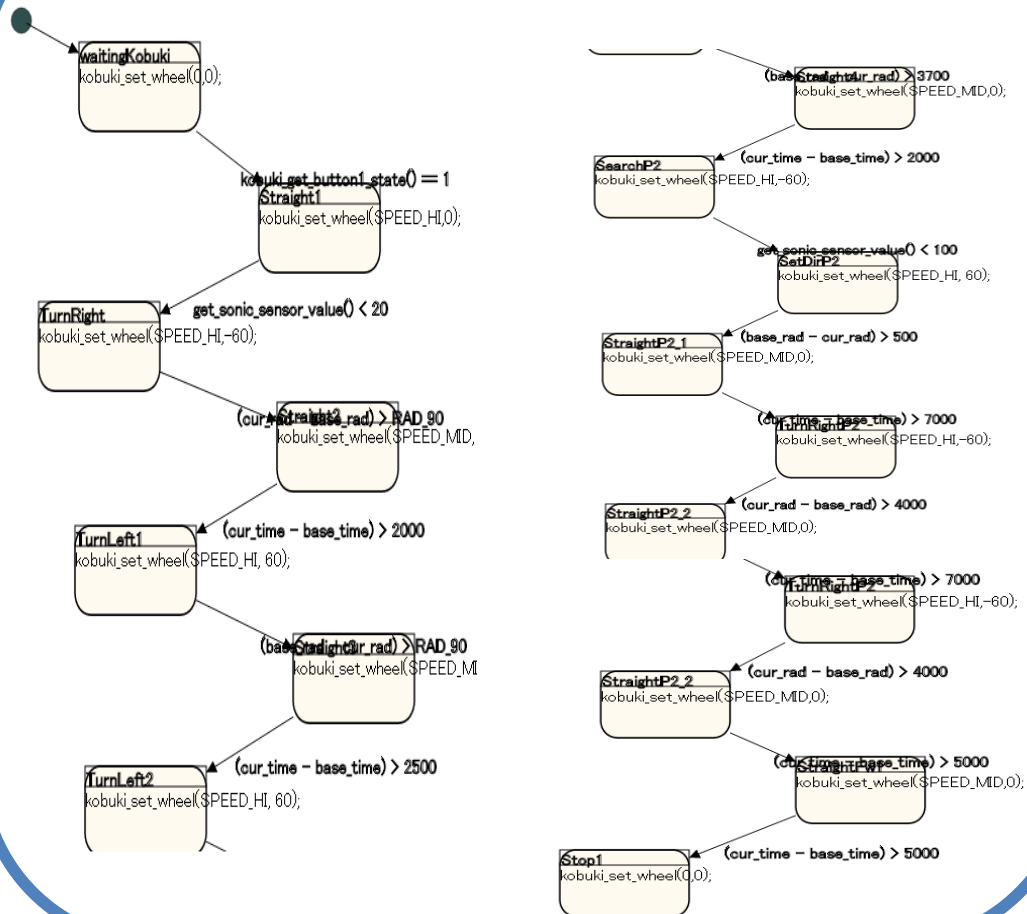
In_Dock

STRAIGHT
TURN_RIGHT
TURN_LEFT
GO_TO_DOCK
STOP_ON_DOCK
BACK

```
kobuki_set_wheel(SPEED_HI,
STRAIGHT);
kobuki_set_wheel(SPEED_HI,
TURN_LEFT);
kobuki_set_wheel(SPEED_HI,
TURN_LEFT);
      .
      .
```

ステートマシン図

Pole_Escape



In_Dock

